## <u>APPENDIX I</u>

% Creating a network topology object % graphically place nodes on screen network topo = topo('init'); 5 % graphically connect up nodes addlink(network topo); % graphically label nodes labelnames(network topo); % save network topo for future use save network topo; 10 % Top level procedure to compute paths that optimize use of network capacity % inputs: D = traffic demand matrix % (retrieved from predictions stored in TMS Statistics Repository) % 15 network topo = topology object defining the network topology % P = network policy information % (matrix of reserved capacity, which indicates links whose use % is administratively prohibited or which should not be % completely allocated) % % outputs: allocated\_paths() = list of paths to set up, to TMS signalling system % % retrieve network topology information C = capacity(network\_topo); 25 C = C - P; Time Time saved C = [];saved SLA = []; assigned paths = []; 30 round = 0;  $[SLA, S] = create ordered_sla(D);$ 35 F = SLA(1)for F = SLA', round = round +1; saved  $C\{\text{round}\} = C;$ saved  $SLA\{round\} = F;$ 40 F % display the flow

W = calc\_weights('calcweight2',F,C);

[dist, P] = floyd(W);

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```
path = findpath(P,F.i,F.j);
                        assigned paths{round}.path = path;
                        assigned_paths{round}.flow = F;
   5
                        if (isempty(path))
                                fprintf(1,'no path for flow:\n'); F
                        else
                                C = compute_residual_capacity('c - F.bw',path,F,C);
  10
                        end
                 end
                 function [W] = calc weights(func,F,C)
  15
                 % function [W] = calc_weights(func,F,C)
                 %
% Compute the weights by calling func on each elt of C
                 % func must be of the form double func(Flow F, Capacity_elt c, node i, node j)
                 func = fenchk(func);
                 for i = 1:size(C,1)
                         for j = 1:size(C,2)
                                 W(i,j) = feval(func,F,C(i,j),i,j);
   25
                         end
                 end
                  function [w] = calcweight2(F,c,i,j)
                  % function [w] = \text{calcweight2}(F,c,i,j)
   30
                  % basic weight calc
                  if(0 == c)
                         w = \inf;
   35
                         return;
                  end
                  % rule out paths that can't hack it
                  if (F.bw > c)
   40
                          w = \inf;
                          return;
                  end
```

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```
w = 1 / (c - F.bw); % fill links with most capacity first
                 function [C] = compute_residual_capacity(func, path, F, C)
                 % function [C] = compute residual capacity(func, path, F, C)
    5
                 %
                 % Update capacity characteristics in C to reflect flow F being
                 \% allocated along path using function func
                     func should be of the form
                        C element func(C element c, Flow F)
                 %
   10
                 if (length(path) \le 1)
                         return;
                 end
   15
                 func = fcnchk(func,'c','F');
index = 1;
                 src = path(index);
                 index = index + 1;
   20
                 for index = index:length(path)
                         dst = path(index);
                         C(src,dst) = feval(func,C(src,dst),F);
   25
                         src = dst;
                  end
function [SLA, S] = create ordered sla(D)
   30
                  % function [SLA] = create ordered_sla(D)
                  % takes the demand matrix and returns a list of SLAs,
                        SLA of the form [ struct ; struct ; ... ] where struct is [BW,i,j]
                  %
                        S of the form [ [BW, i, j]; [BW, i, j]; ...]
                  %
    35
                  S = [];
                  for i = 1:size(D,1)
                          for i = 1:size(D,2)
    40
                                 if (D(i,j) \sim 0)
                                         S = [[D(i,j) i j]; S];
                                  end
                          end
                  end
    45
```

```
[Y, I] = sortrows(S,1);
                  S = Y(size(Y,1):-1:1,:); % reverse order
    5
                   SLA = struct('bw',num2cell(S(:,1)),'i',num2cell(S(:,2)),'j',num2cell(S(:,3)));
                   return;
   10
                   function [path] = findpath(P,i,j)
                   % function [path] = findpath(P)
                   %
                   %
   15
                   path = [];
                   if(i == j)
20
20
25
30
30
                           path = [i];
                           return;
                   end
                   if (0 == P(i,j))
                           path = [];
                   else
                           path = [findpath(P,i,P(i,j)) j];
                   end
                   function [D, P] = floyd(W)
                   % function [D, P] = floyd(W)
   30
                   % given weights Wij, compute min dist Dij between node i to j
                   % on shortest path from i to j, j has immeadiate predecessor Pij
                   n = size(W,1);
                   if (n \sim = size(W,2))
    35
                           error('Input W is not square??!!');
                   end
                   D = W;
                   P = repmat([1:n]',[1:n]);
    40
                   P = P \cdot * \sim isinf(W);
                   P = P .* \sim eye(n);
                   for k = 1:n
                           for i = 1:n
    45
```

```
for \ j = 1:n
alt\_path = D(i,k) + D(k,j);
if \ (D(i,j) > alt\_path)
D(i,j) = alt\_path;
P(i,j) = P(k,j);
end
end
k;
10
D;
P;
end
```

## **APPENDIX II**

```
function addlink(TOPO)
                  % addlink(TOPO)
                  %
    5
                  % interactively add links to the TOPO
                  update(TOPO);
                  c src = 1;
                  c dst = 2;
   10
                  c bw = 3;
                  figure(TOPO.cur fig)
                  while (1)
   15
                  fprintf(1,'\n\nHit Button 3 to end...\n\n');
% find coords and index i of src
                  [x1i y1i button] = ginput(1);
                  if (button == 3) break; end
                  d = sqrt((TOPO.locs(:,1) - x1i).^2 + (TOPO.locs(:,2) - y1i).^2);
                  [d,i] = \min(d);
                  x1 = TOPO.locs(i,1); y1 = TOPO.locs(i,2);
                  % find coords and index j of dst
                  [x2i y2i] = ginput(1);
                  d = sqrt((TOPO.locs(:,1) - x2i).^2 + (TOPO.locs(:,2) - y2i).^2);
                  [d,j] = \min(d);
                  x2 = TOPO.locs(j,1); y2 = TOPO.locs(j,2);
   30
                  hold on;
                  lh = line([x1 x2],[y1 y2],'color','red');
    35
                  cap = input('Enter capacity (in Mbps) > ');
                  fprintf(1,'About to create symetric %d Mbps link from node %d to node %d\n',cap,i,j);
                  doit = input('Enter Y to confirm, N to reject, and B to change bandwidth (Y)>','s');
    40
                  if (isempty(doit)) doit = 'Y'; end
                  if (doit == 'n' | doit == 'N')
                          delete(lh);
    45
                          return;
```

```
end
                  if (doit == 'b' | doit == 'B')
                          buf = sprintf('Enter capacity from %d to %d (in Mbps) > ',i,j);
     5
                          cap i to j = input(buf);
                          buf = sprintf('Enter capacity from %d to %d (in Mbps) > ',j,i);
                          cap_j to_i = input(buf);
                  else
    10
                          cap i to j = cap;
                          cap_j_{to_i} = cap;
                   end
                  %build the link records
    15
                  clear linkab linkba;
linkab.src = i;
                  linkab.dst = j;
                   linkab.bw = cap i to j;
    20
                   linkab.handle = lh;
                   linkba.src = j;
                  linkba.dst = i;
                  linkba.bw = cap_j_to_i;
    25
                   linkba.handle = lh;
                   % now draw the actual link on the map
                   delete(lh);
    30
                   lh = drawlink(TOPO, linkab);
                   % now store the link info
                   TOPO.links = [TOPO.links; linkab; linkba];
                   TOPO.linkarray = [TOPO.linkarray; [ijcap_i_to_j]; [jicap_j_to_i]];
    35
                   end % of while loop
                   assignin('caller',inputname(1),TOPO);
    40
                   function [C, portmap] = capacity(TOPO)
     45
                   % [C, portmap] = capacity(TOPO)
```

```
% portmap maps indices of C to elts of nodes(TOPO)
                 %
                        [node dir] where
                               node is index of elt in nodes(TOPO)
                 %
                               dir is 1 if data enters here, -1 if data leaves here
                 %
    5
                 numnodes = length(TOPO.links) * 2;
                 C = zeros(numnodes,numnodes);
   10
                 curnode = 0;
                 portmap = [];
                 for i = 1:length(TOPO.links)
                         link = TOPO.links(i);
                         curnode = curnode + 1;
   15
                         portmap(curnode,:) = [link.src -1];
                         curnode = curnode + 1;
                         portmap(curnode,:) = [link.dst 1];
C(curnode-1,curnode) = link.bw;
   20
                 end
                  c node = 1;
                  c_{dir} = 2;
   25
                  for i = 1:length(TOPO.nodes)
                         ins = find(portmap(:, c node) == i & portmap(:, c dir) == 1);
                         outs = find(portmap(:,c node) == i & portmap(:,c dir) == -1);
                         for j = ins
   30
                                for k = outs
                                        C(j,k) = inf;
                                end
                         end
                  end
   35
                  function [a, b, c] = debug(t)
                  update(t);
                  fieldnames(t)
   40
                  a = t.nodes
                  b = t.locs
                  c = t.links
                  function display(TOPO)
   45
                  % DISPLAY a topo object
```

```
% a link is a unidirectional, so the value is probably twice what you want
                  fprintf('[TOPO object: %d nodes %d links]\n',...
                        length(TOPO.nodes),length(TOPO.links));
                 function draw(TOPO)
     5
                 % draw(topo)
                 %
                 % draw the topology figure in a new window
   10
                 TOPO.cur fig = figure;
                 axis(TOPO.axis);
                 axis equal:
                 axis manual;
                 box on;
   15
                 hold on;
for i = 1:length(TOPO.nodes)
                        nm = plot(TOPO.nodes\{i\}.loc(1),TOPO.nodes\{i\}.loc(2),'ob');
                        TOPO.nodes{i}.mark handle = nm;
   20
                        if (isfield(TOPO.nodes{i},'nameloc'))
                                TOPO.nodes\{i\}.nameloc(3) = text(TOPO.nodes\{i\}.nameloc(1),...
                                             TOPO.nodes{i}.nameloc(2),TOPO.nodes{i}.name);
                         end
                  end
   25
                  % yes, this draws the same link twice. fix it if it matters -dam 11/21
Hall Hall
TOPO.linkarray = \{ \};
7
                  for i = 1:length(TOPO.links)
į.
    30
                         TOPO.links(i).handle = drawlink(TOPO,TOPO.links(i));
                         TOPO.linkarray = [TOPO.linkarray; ...
                                 [ TOPO.links(i).src TOPO.links(i).dst TOPO.links(i).bw]];
                  end
                  assignin('caller',inputname(1),TOPO);
   35
                  function ex(t)
                  t.nodes
                  function labelnames(TOPO)
                  % function labelnames(TOPO)
    40
                  % make it easy to label the nodes
                  for i = 1:length(TOPO.nodes)
                         fprintf('Place label for node %d "%s"\n',i,char(TOPO.nodes{i}.name));
    45
```

```
origcolor = get(TOPO.nodes{i}.mark handle,'color');
                                                                   set(TOPO.nodes{i}.mark handle,'color',[1 0 0]);
                                                                   if (isfield(TOPO.nodes{i},'nameloc'))
                                                                                      good x = TOPO.nodes\{i\}.nameloc(1);
             5
                                                                                      good y = TOPO.nodes\{i\}.nameloc(2);
                                                                   end
                                                                   th = [];
                                                                   while (1)
          10
                                                                                      fprintf('Button 1 to (re)place text, Button 3 to accept\n');
                                                                                      [x,y,button] = ginput(1);
                                                                                      if (3 == button) break; end
                                                                                      if (~isempty(th)) delete(th); end
                                                                                      th = text(x,y,TOPO.nodes\{i\}.name);
           15
                                                                                      good x = x; good y = y;
                                                                   end
The state of the s
                                                                    TOPO.nodes{i}.nameloc = [good x, good y, th];
                                                                   set(TOPO.nodes{i}.mark handle,'color',origcolor);
                                                end
                                                assignin('caller',inputname(1),TOPO);function names(TOPO)
                                                % NAMES the list of names of the nodes in the topo
                                                fprintf('Node\t\tName\n');
In the mention of the
          25
                                                for i = 1:size(TOPO.names,1)
                                                                    fprintf('%d\t\t%s\n',i,TOPO.names{i});
                                                end
                                                function [node] = nodes(TOPO)
                                                % function [node] = nodes(TOPO)
           30
                                                        returns a cell array describing nodes in the TOPO
                                                node = TOPO.nodes;
                                                function [TOPO] = topo(TOPO)
                                                %[TOPO] = topo(TOPO)
           35
                                                %% if input TOPO is 'init', create a new topology
                                                %
                                                %
                                                                         newtopo = topo('init');
                                                 %
                                                          else add new nodes to TOPO
           40
                                                % nodes is a array of structs, one per node
                                                % link is a array of structs, one per link
                                                %
                                                                    a link is a unidirectional item, so there are probably twice
                                                %
                                                                    as many links as you'd expect.
           45
```

```
if (nargin < 1)
                      error('topo(TOPO) or topo("init") - not enough args');
               end
               if (ischar(TOPO) & TOPO == 'init')
  5
                       clear TOPO
                       TOPO.nodes = [];
                       TOPO.links = [];
  10
                                              % now computed as needed
                       TOPO.capacity = [];
                                            % internal cache
                       TOPO.locs = [];
                                              % internal cache
                       TOPO.linkarray = [];
                       f = figure;
  15
                       axis([0 75 0 50]);
                       TOPO.axis = axis;
TOPO.cur fig = f;
                        axis equal
                        axis manual
                        box on
                        hold
                 else
                        figure(TOPO.cur_fig);
   25
                 end
                 nodecount = length(TOPO.nodes);
   30
                 while (1)
                         clear nodeinfo;
                         fprintf(1, \n Button 3 to stop \n');
                         [x \ y \ but] = ginput(1);
                         if (but == 3) break; end
    35
                         x = floor(x); y = floor(y);
                         nm = plot(x,y,'ob');
                         name = input('Enter name > ','s');
                         nodeinfo.loc = [x y];
    40
                         nodeinfo.mark_handle = nm;
                         nodeinfo.name = cellstr(name);
                         nodecount = nodecount + 1;
                          TOPO.nodes{nodecount} = nodeinfo;
                  end
    45
```

```
if ('topo' \sim= class(TOPO))
                         TOPO = class(TOPO, 'topo');
                  end
     5
                  if (nargout == 0)
                         assignin('caller',inputname(1),TOPO);
                  end
                  function lh = drawlink(TOPO, link)
   10
                  % assumes TOPO.linkarray is already valid, and draws the position of
                  % link line based on the number of links already present in linkarray
                  c src = 1;
                  c dst = 2;
    15
                  c bw = 3;
i = link.src;
                  i = link.dst;
    20
                  x1 = TOPO.nodes{i}.loc(1);
                  y1 = TOPO.nodes{i}.loc(2);
                  x2 = TOPO.nodes{j}.loc(1);
                  y2 = TOPO.nodes\{j\}.loc(2);
   25
                  if (isempty(TOPO.linkarray))
                         num_links = 0;
                  else
                         num links = sum(TOPO.linkarray(:,c src) = i & TOPO.linkarray(:,c dst) == j);
    30
                  end
                  pattern = [01 - 12 - 23 - 3] * .3;
                  if (abs(x1 - x2) > abs(y1 - y2))
    35
                          delta x = 0;
                          delta y = pattern(num links + 1);
                  else
                          delta x = pattern(num links + 1);
                          delta y = 0;
    40
                  end
                  1h = line([x1 \ x2] + delta \ x, [y1 \ y2] + delta \ y, 'color', 'black');
                  function update(TOPO)
```

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```
clear TOPO.locs;
                 for i = 1:length(TOPO.nodes)
                        TOPO.locs(i,:) = TOPO.nodes\{i\}.loc
                 end
    5
                 clear TOPO.linkarray;
                 for i = 1:length(TOPO.links)
                         TOPO.linkarray = [TOPO.linkarray; ...
                                 [ TOPO.links(i).src TOPO.links(i).dst TOPO.links(i).bw]];
   10
                 end
                 % these are here to be cut and pasted into other functions as needed
                 % there doesn't seem to be a good way to pass them around in another fashion
                 % (using assigning('caller'...) to force their definition sounds like asking
                 % for trouble 'cause you'll overwrite another definition of them...)
   15
                 c_{src} = 1;
c_dst = 2;
                 c bw = 3;
                 assignin('caller',inputname(1),TOPO);
Hang.
```